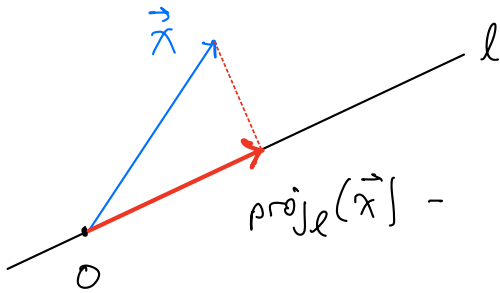


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Last time:

Orthogonal Projections in the Plane  $\mathbb{R}^2$ 

$$\text{proj}_l(\vec{x}) = (\vec{x} \cdot \vec{u}) \vec{u} \quad \text{where } \vec{u} = \frac{1}{\|\vec{w}\|} \vec{w} \quad \leftarrow \text{this should be memorized}$$

In fact it's a linear transformation:

$$\text{say } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad \vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}.$$

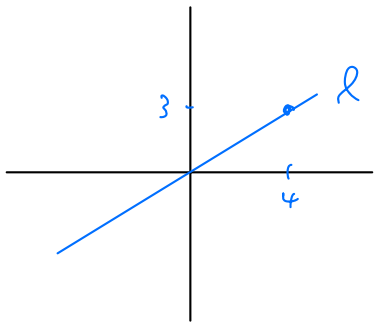
$\leftarrow$  unit vector

then

$$\text{proj}_l(\vec{x}) = \begin{bmatrix} u_1^2 & u_1 u_2 \\ u_1 u_2 & u_2^2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad (\star)$$

Ex let  $l$  be the line  $3x - 4y = 0$ .Find the matrix giving  $\text{proj}_l(\vec{x})$ .

[The question could also say let  $l$  be the line joining  $0$  and  $\begin{bmatrix} 4 \\ 3 \end{bmatrix}$ .]



$l$  contains  $\vec{w} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$

Note  $\|\vec{w}\| = \sqrt{4^2 + 3^2} = 5$

So  $u = \frac{\vec{w}}{\|\vec{w}\|} = \begin{bmatrix} 4/5 \\ 3/5 \end{bmatrix}$  is a unit vector on  $l$ .

$\Rightarrow \text{proj}_l(\vec{x}) = (\vec{x} \cdot \vec{u}) \vec{u}$  is defined by (\*)

$$\text{proj}_l \left( \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} 16/25 & 12/25 \\ 12/25 & 9/25 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad (\text{answer})$$

For the purpose of the next remark, note  $\rightarrow$

$$\left[ \frac{4}{25} \begin{bmatrix} 4 \\ 3 \end{bmatrix} \mid \frac{3}{25} \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

scalar multiples of the same vector,  $\begin{bmatrix} 4 \\ 3 \end{bmatrix}$

Important observation about projection to a line in  $\mathbb{R}^n$ :

$$A = \left[ T(\vec{e}_1) \mid \dots \mid T(\vec{e}_n) \right]$$

If this represents projection to  $l$  (which goes thru the origin) then  $T(\vec{e}_1), \dots, T(\vec{e}_n)$  all lie on  $l$ , so the columns of  $A$  must be scalar multiples of each other!

The goal of the rest of §2.2 is to similarly analyze similar linear transformations for  $\mathbb{R}^2$  and  $\mathbb{R}^3$ . We'll look at the main ideas.

List of topics:

reflections in  $\mathbb{R}^2$  about a line thru the origin

" "  $\mathbb{R}^3$  " " " plane " " "

" " " " " line " " "

orthog. projections to a plane in  $\mathbb{R}^3$  (thru the origin)

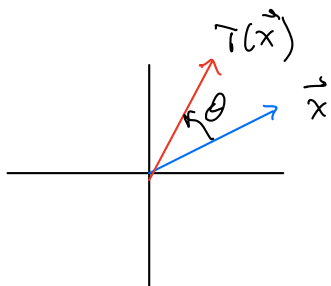
" " " " line in  $\mathbb{R}^3$  " " "

rotations in  $\mathbb{R}^2$  about the origin

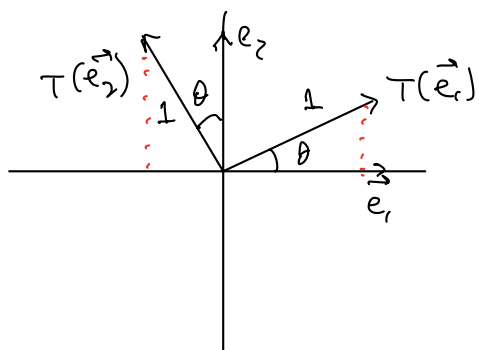
shears in  $\mathbb{R}^2$

Plus combinations of these.

Start with rotations in  $\mathbb{R}^2$ . (Quick)



So focus on  $\vec{e}_1$  and  $\vec{e}_2$



$$T(\vec{e}_1) = \begin{bmatrix} \cos\theta \\ \sin\theta \end{bmatrix}$$

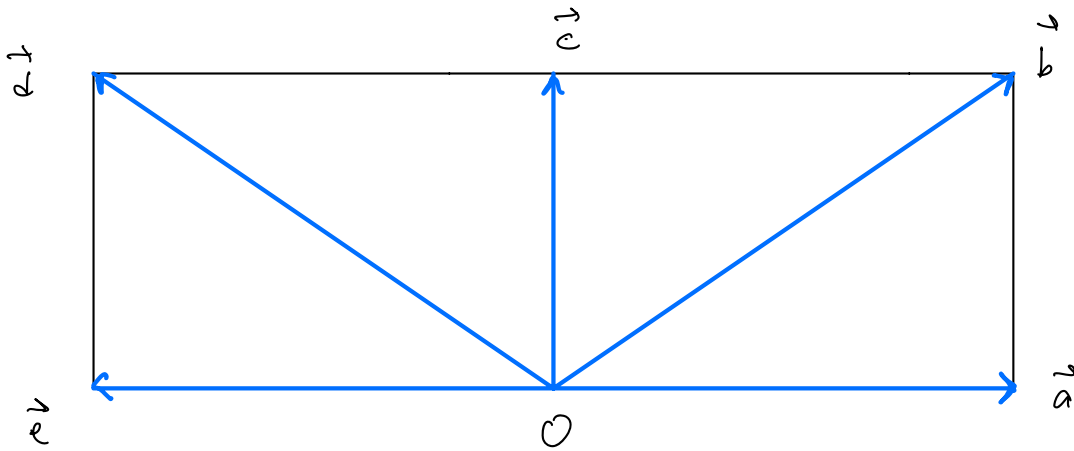
$$T(\vec{e}_2) = \begin{bmatrix} -\sin\theta \\ \cos\theta \end{bmatrix}$$

so the matrix for T is

$$\begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

Now come back to the others.

As a preparation, note (assume the rectangles are isomorphic)



then

- $\vec{a} + \vec{c} = \vec{b}$
- $\vec{a} + \vec{d} = \vec{c}$
- $\vec{a} + \vec{e} = \vec{0}$
- $\vec{b} + \vec{d} = 2\vec{c}$  (this takes a moment's thought)

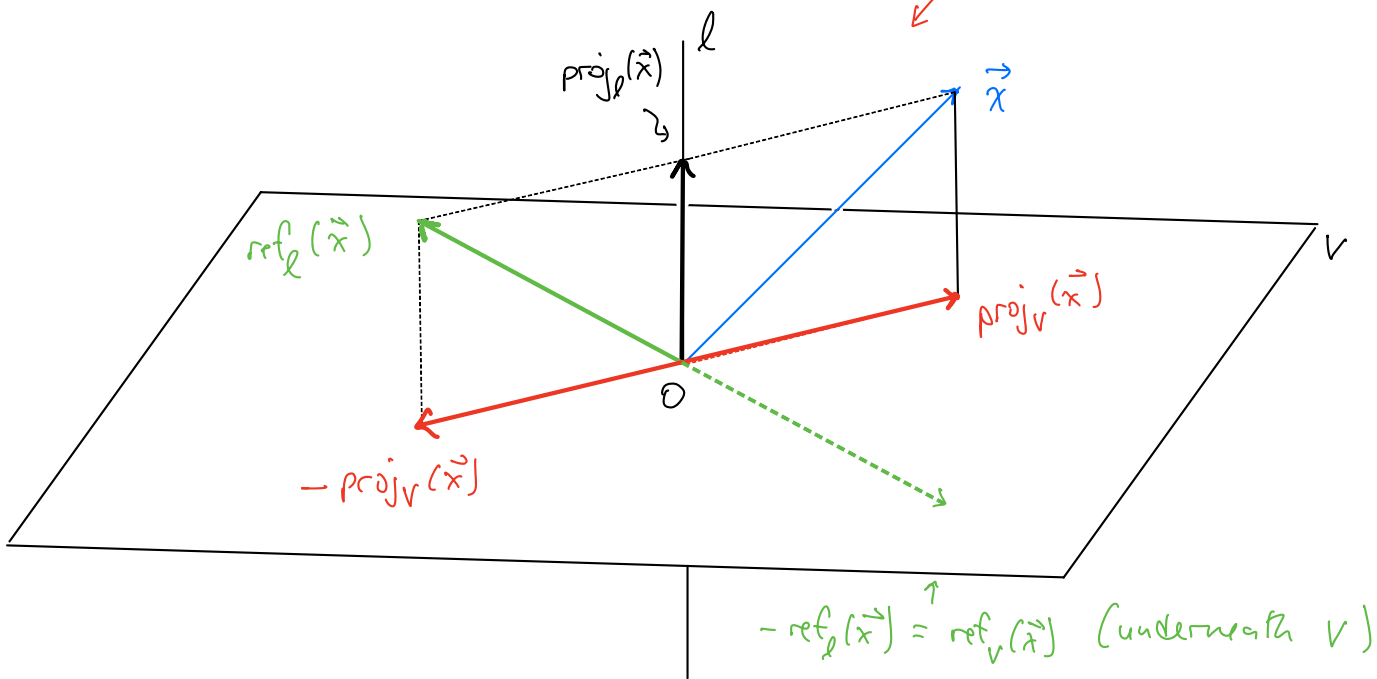
These hold whether the picture is in  $\mathbb{R}^2$  or is any plane through the origin in  $\mathbb{R}^3$ .  
(or  $\mathbb{R}^n$ )

let's look in  $\mathbb{R}^3$ . let  $l$  be a line thru the origin. let  $V = l^\perp$

be the plane thru the origin perp. to  $l$ . The following picture defines

some of the main constructions

← this is a copy of the previous picture!



Connections (Don't memorize, but understand.) (Use these for HW.)

The parallelograms are actually rectangles, viewed with perspective.

$$\text{let } u = \frac{1}{\|\vec{w}\|} \vec{w}.$$

Then using the rectangle above we get the following

$$(i) \quad \text{proj}_l(\vec{x}) = (\vec{x} \cdot \vec{u}) \vec{u} \quad \text{where } u = \frac{1}{\|\vec{w}\|} \vec{w}.$$

$$(ii) \quad \text{proj}_V(\vec{x}) = \vec{x} - \text{proj}_l(\vec{x}) = \vec{x} - (\vec{x} \cdot \vec{u}) \vec{u}$$

$$(iii) \quad \text{ref}_l(\vec{x}) + \text{proj}_V(\vec{x}) = \text{proj}_l(\vec{x})$$

$$\Rightarrow \quad \text{ref}_l(\vec{x}) = \text{proj}_l(\vec{x}) - \text{proj}_V(\vec{x}) \quad (\text{but see (iii)})$$

$$(iii) \quad \text{ref}_l(\vec{x}) + \vec{x} = 2 \text{proj}_l(\vec{x})$$

$$\Rightarrow \quad \text{ref}_l(\vec{x}) = 2 \text{proj}_l(\vec{x}) - \vec{x} = 2(\vec{x} \cdot \vec{u}) \vec{u} - \vec{x} \quad (\text{more useful than (iii)})$$

$$(iv) \quad \text{ref}_V(\vec{x}) + \text{proj}_L(\vec{x}) = \text{proj}_V(\vec{x})$$

$$(v) \quad \text{ref}_V(\vec{x}) + \text{ref}_L(\vec{x}) = \vec{0}$$

$$\Rightarrow \text{ref}_V(\vec{x}) = \text{proj}_V(\vec{x}) - \text{proj}_L(\vec{x}) \quad (\text{by (iv)})$$

$$= -\text{ref}_L(\vec{x}) \quad (\text{by (v)})$$

$$= \vec{x} - 2(\vec{x} \cdot \vec{u})\vec{u} \quad (\text{by (iii)})$$